

Dynamic Classifier Systems for Classifier Aggregation

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Seminář z umělé inteligence
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Outline

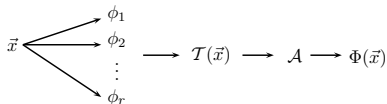
- 1 Classifier Combining
- 2 Classification Confidence
- 3 Classifier Systems
- 4 Experiments
- 5 Assessing Confidence Measures

Classification

- classification – process of assigning *patterns* into *classes*
- \mathcal{X} – feature space, \vec{x} pattern
- C_1, \dots, C_N – classes
- classifier – mapping $\phi : \mathcal{X} \rightarrow [0, 1]^N$
 $\phi(\vec{x}) = (\mu_1(\vec{x}), \dots, \mu_N(\vec{x}))$
- $\mu_i(\vec{x})$ – degree of classification $x \in C_i$
- interpretation of $\mu_i(\vec{x})$ – depends on the classifier used
(probability, fuzzy membership, ...)

Classifier Combining

- method for improving the classification by using multiple classifiers and combining their outputs
- create a team $\mathcal{T} = (\phi_1, \dots, \phi_r)$ of classifiers (bagging, boosting, ...)
- aggregate the team using aggregator \mathcal{A}
- most of the aggregation methods are *static*



Classification example



- C_1 – bananas, C_2 – apples

Classification example ctnd.



- $\phi(\vec{x}) = (0.1, 0.8)$

Classification example ctnd.



- $\phi(\vec{x}) = (0.9, 0.1)$

Classification example ctnd.



- $\phi(\vec{x}) = (0.1, 0.2)$
- *Low confidence*

Classification Confidence

- degree of trust we can give to the classifier ϕ
- probability of correct classification of \vec{x} by ϕ
- ability to answer "I don't know"
- confidence measure $\kappa_\phi : \mathcal{X} \rightarrow [0, 1]$
- static measures – constant of the classifier (e.g., accuracy)
- dynamic measures – adapted to the currently classified pattern (e.g., local accuracy)

Global Accuracy - GA

- static confidence measure
- validation (training) set \mathcal{M}
- proportion of patterns $\vec{y} \in \mathcal{M}$ correctly classified by ϕ

$$\kappa_{\phi}^{(GA)}(\vec{x}) = \frac{\sum_{\vec{y} \in \mathcal{M}} I(\phi_{cr}(\vec{y}) \stackrel{?}{=} c(\vec{y}))}{|\mathcal{M}|}$$

Euclidean Local Accuracy - ELA

- dynamic confidence measure
- validation (training) set \mathcal{M}
- $N(x)$ patterns from \mathcal{M} neighboring with \vec{x} (e.g., 20 nearest under Euclidean metric)
- proportion of patterns $\vec{y} \in N(\vec{x})$ correctly classified by ϕ

$$\kappa_{\phi}^{(ELA)}(\vec{x}) = \frac{\sum_{\vec{y} \in N(\vec{x})} I(\phi_{cr}(\vec{y}) \stackrel{?}{=} c(\vec{y}))}{|N(\vec{x})|}$$

Euclidean Local Match - ELM

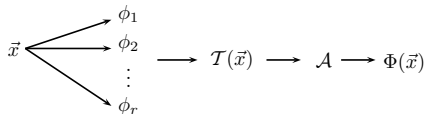
- dynamic confidence measure
- validation (training) set \mathcal{M}
- $N(x)$ patterns from \mathcal{M} neighboring with \vec{x} (e.g., 20 nearest under Euclidean metric)
- proportion of patterns $\vec{y} \in N(\vec{x})$ from the same class as ϕ is predicting for \vec{x}

$$k_{\phi}^{(ELM)}(\vec{x}) = \frac{\sum_{\vec{y} \in N(\vec{x})} I(\phi_{cr}(\vec{x}) \stackrel{?}{=} c(\vec{y}))}{|N(\vec{x})|}$$

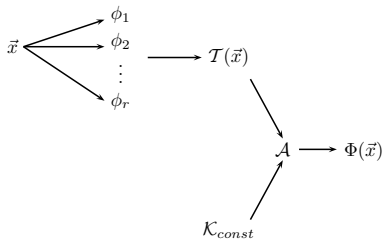
Classifier Systems

- $\mathcal{S} = (\mathcal{T}, \mathcal{K}, \mathcal{A})$ – classifier system
- $\mathcal{T} = (\phi_1, \dots, \phi_r)$ – classifiers
- $\mathcal{K} = (\kappa_{\phi_1}, \dots, \kappa_{\phi_r})$ – confidence measures
- \mathcal{A} – aggregator
- 3 types of classifier systems
 - confidence-free
 - static
 - dynamic

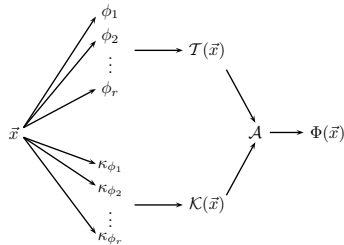
Types of classifier systems



(a) Confidence-free



(b) Static



(c) Dynamic

Mean value based aggregators

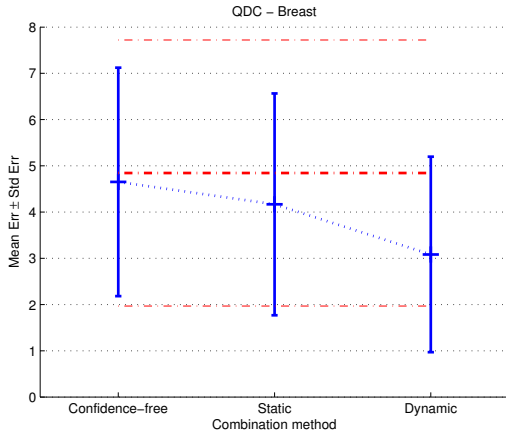
- confidence-free – mean value of the classifier outputs
- static – weighted mean; weights are static confidences
- dynamic – weighted mean; weights are dynamic confidences

$$T(\vec{x}) = \begin{pmatrix} \phi_1(\vec{x}) \\ \phi_2(\vec{x}) \\ \vdots \\ \phi_r(\vec{x}) \end{pmatrix} = \begin{pmatrix} \mu_{1,1}(\vec{x}) & \mu_{1,2}(\vec{x}) & \dots & \mu_{1,N}(\vec{x}) \\ \mu_{2,1}(\vec{x}) & \mu_{2,2}(\vec{x}) & \dots & \mu_{2,N}(\vec{x}) \\ & & \ddots & \\ \mu_{r,1}(\vec{x}) & \mu_{r,2}(\vec{x}) & \dots & \mu_{r,N}(\vec{x}) \end{pmatrix}, \mathcal{K}(\vec{x}) = \begin{pmatrix} \kappa_{\phi_1}(\vec{x}) \\ \kappa_{\phi_2}(\vec{x}) \\ \vdots \\ \kappa_{\phi_r}(\vec{x}) \end{pmatrix}$$

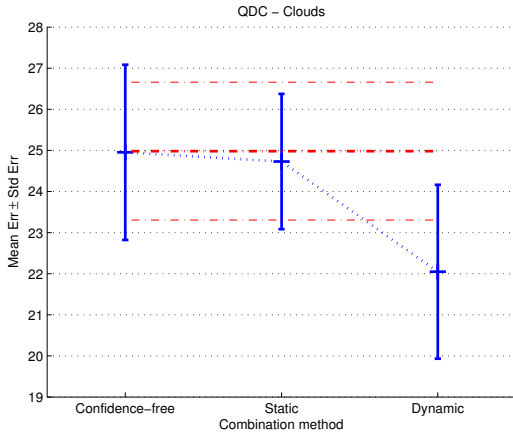
Experiments

- comparison: confidence-free vs. static vs. dynamic systems
- systems of Quadratic Discriminant Classifiers
- various confidence measures
- aggregators based on mean value aggregator
- 4 artificial, 4 real-world datasets
- 10-fold crossvalidation
- ELM confidence measure

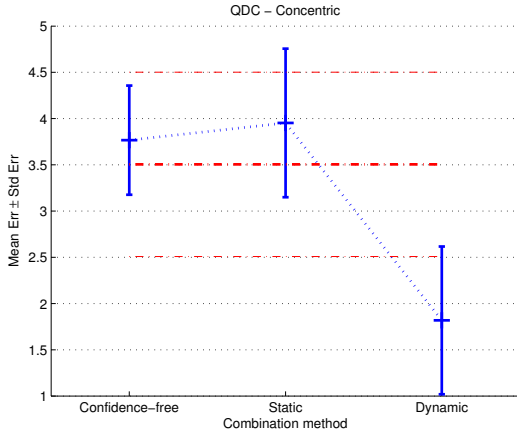
Results – QDC



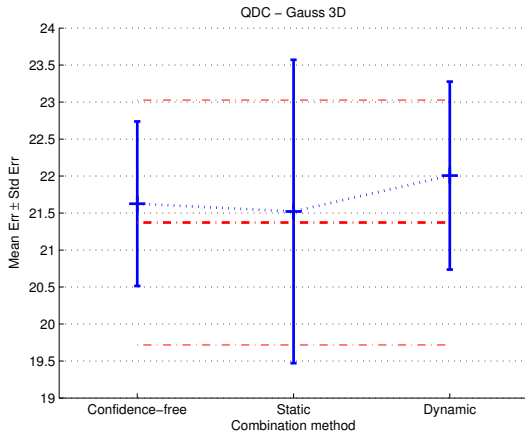
Results – QDC



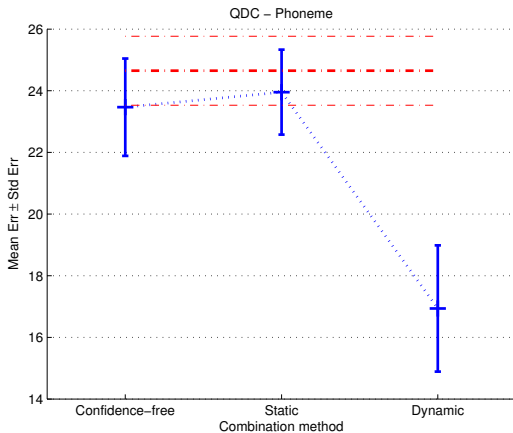
Results – QDC



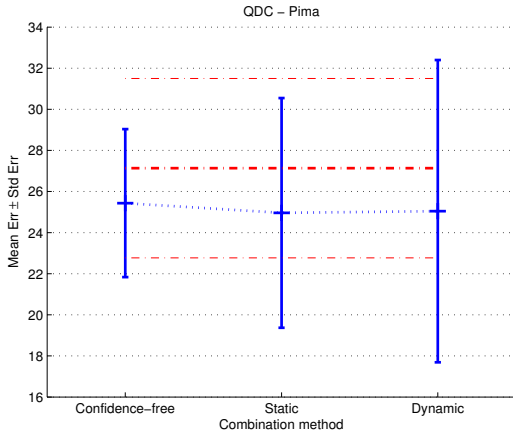
Results – QDC



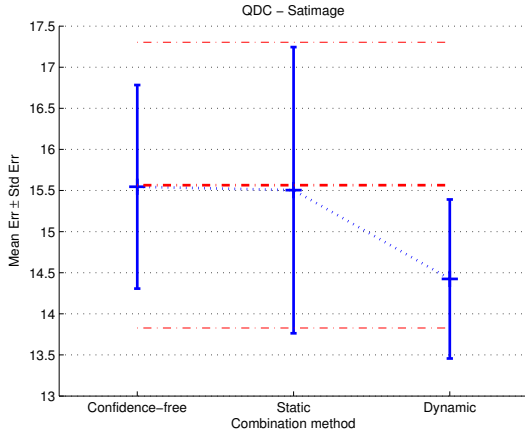
Results – QDC



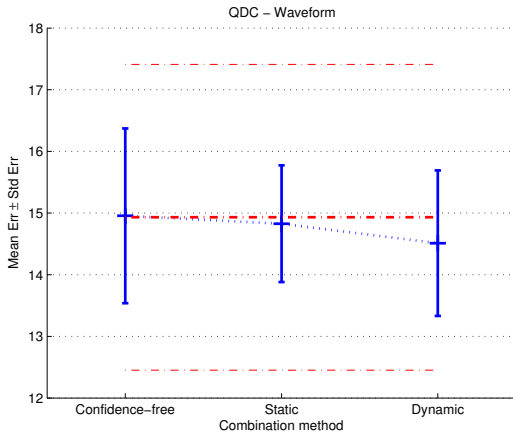
Results – QDC



Results – QDC



Results – QDC



Experiments - Results

- experiments with QDC ensembles: dynamic classifier systems can significantly improve classification quality
- similar results with Random Forests on 17 datasets
- improvement in classification quality vs. higher computational complexity
- ELM more successful than ELA

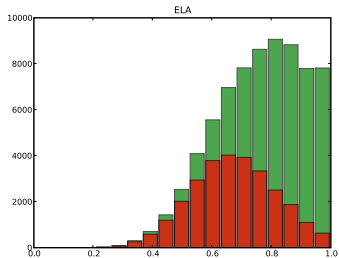
Assessing Confidence Measures

- which confidence measure is better?
- will a confidence measure bring improvement in the classification quality?
- are the benefits of a dynamic classifier system worth bigger computational complexity?

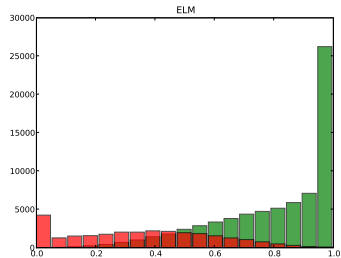
OK/NOK Histograms

- confidence measure = probability of correct classification?
- distribution of correctly classified patterns (OK)
- distribution of correctly classified patterns (NOK)
- OK and NOK should not overlap and should be separated

OK/NOK Histograms – Waveform

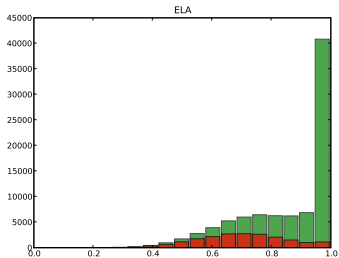


(d) ELA – bad separation

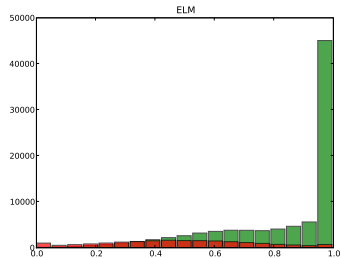


(e) ELM – relatively good separation

OK/NOK Histograms – Phoneme



(a) ELA

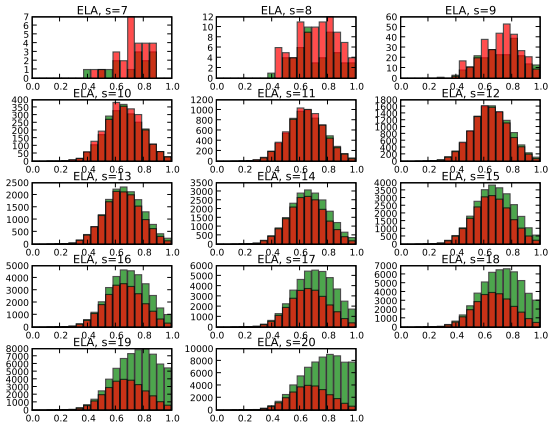


(b) ELM

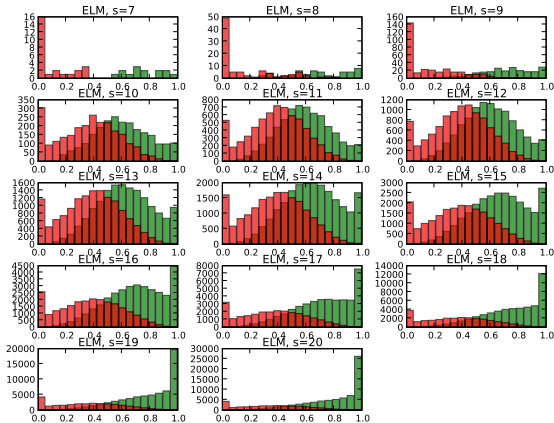
Restricted Histograms

- sometimes the OK/NOK histograms do not correlate with improvement in the prediction
- for most of the patterns, the classifiers give similar outputs \Rightarrow the OK/NOK separation is irrelevant
- restrict the testing set to “unclear” patterns $U(s)$
- $0 \leq s \leq r$... degree of consensus
- for any class, at most s classifiers vote for the class
- OK/NOK histograms restricted to $U(s)$

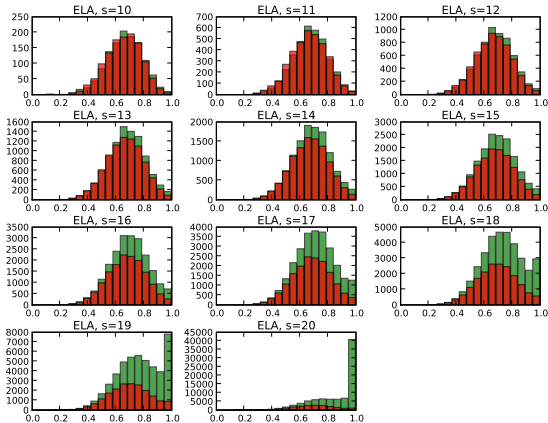
Restricted Histograms – Waveform



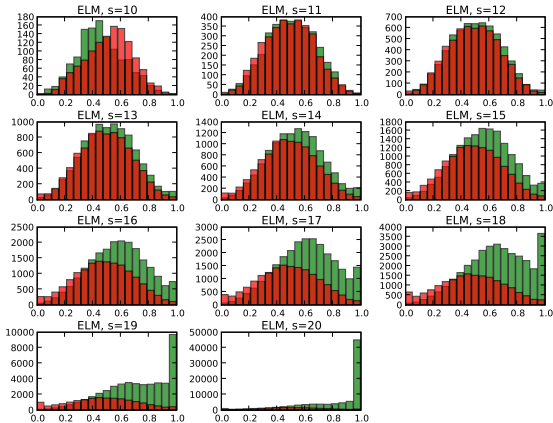
Restricted Histograms – Waveform



Restricted Histograms – Phoneme



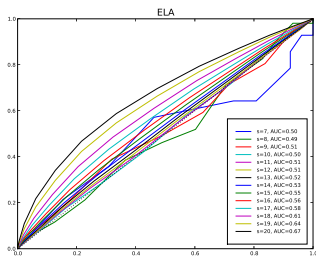
Restricted Histograms – Phoneme



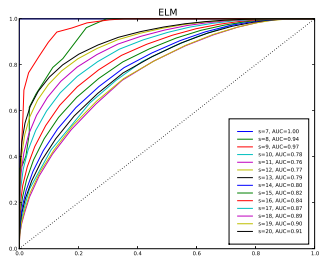
ROC analysis

- convert the histograms to a ROC curve
- summary – area under ROC (AUC)
- $AUC = 50\%$ – random guessing
- $AUC = 100\%$ – ideal

OK/NOK ROCs – Waveform

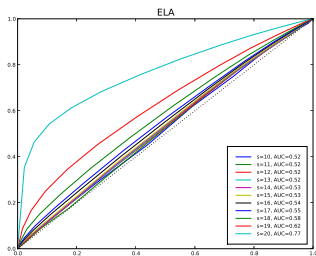


(a) ELA

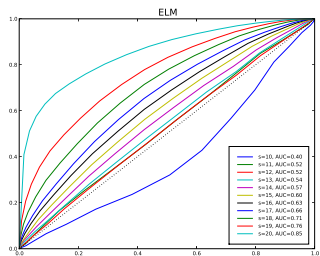


(b) ELM

OK/NOK ROCs – Phoneme



(a) ELA

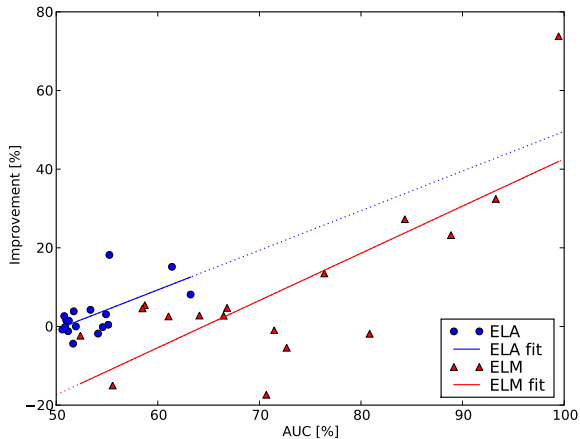


(b) ELM

Improvement vs. AUC

- AUC for $U(s)$ covering 5% of the data
- improvement of DWM over MV
- better AUC $\stackrel{?}{\Rightarrow}$ better improvement?
- scatterplot for 17 datasets

Improvement vs. AUC



Conclusions & Future Work

- formalism of classifier systems with classification confidence
- 3 types of classifier systems
- experiments with QDCs and RFs: dynamic systems can outperform both static and confidence-free systems
- methods for assessing confidence measures
- future work: different classifier types (SVM)
- future work: more advanced aggregation methods
- better methods for assessing confidence measures

Thank you for your attention



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